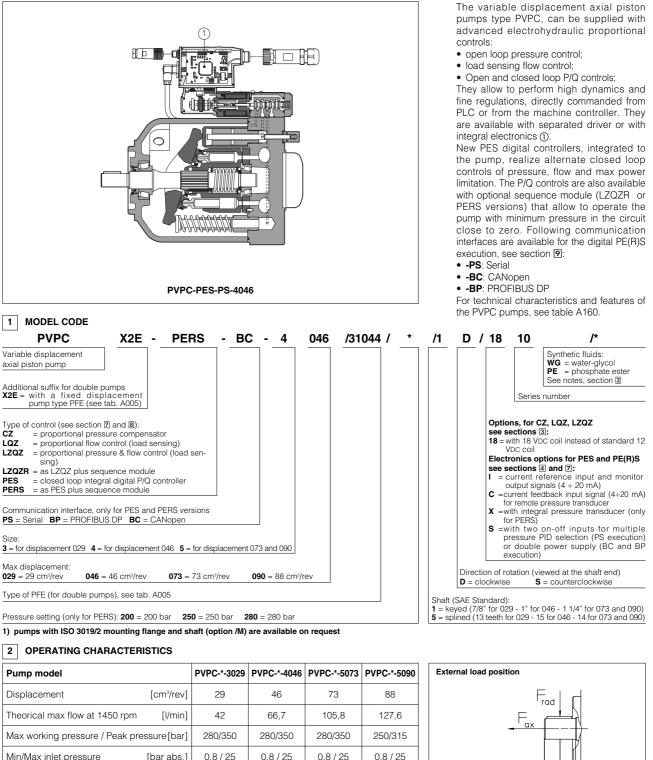
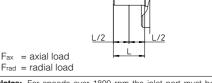


Proportional electrohydraulic controls for PVPC pumps

pressure-flow alternate P/Q controls, analog or digital



0.8/25 0.8 / 25 0,8/25 0,8/25 [bar abs.] Max pressure on drain port [bar abs.] 1,5 1,5 1,5 1,5 Power consumption at 1450 rpm and at [kW] 19,9 31,6 50,1 54,1 maximum pressure and displacement Type 1 Type 5 Type 1 Type 5 Type 1 Type 5 ype 1 Type 5 T Max torque on the first shaft [Nm] 220 155 190 330 400 620 400 620 Max permissible load Fax 2000 1000 1500 2000 on drive shaft 3000 300 1500 1500 600 ÷ 3000 600 ÷ 2600 600 ÷ 2200 600 ÷ 1850 Speed rating [rpm]



Notes: For speeds over 1800 rpm the inlet port must be under oil level with adequate pipes Maximum pressure for all models with option /WG is 160

bar, with option /PE is 190 bar. with options /WG and /PE

speed is 2000/1900/1600/1500 rpm respectively for the four sizes.

3 MAIN CHARACTERISTICS OF VARIABLE DISPLACEMENT AXIAL PISTON PUMP TYPE PVPC

Any position. The drain port must be on the top of the pump. Drain line must be separated and unrestricted to the reservoir and extended below the oil level as far from the inlet as possible. Suggested maximum line lenght is 3 m.					
from -20°C to +70°C for versions with separated electronics / from -20°C to + 60°C for versions PES/PERS					
Hydraulic oil as per DIN 51524535; for other fluids see section 1					
15÷100 mm ² /sec at 40°C (ISO VG 15÷100). Maximum start-up viscosity: 1000 mm ² /sec					
ISO 16/13 (filters at 10 μ m value with $\beta_{10} \ge 75$ recommended)					
-20°C +60°C -20°C +50°C (seals /WG) -20°C +80°C (seals /PE)					
PERS) 24 Vbc					

3.1 Coils characteristics - only for CZ, LQZ, LZQZ(R) executions

	•, ••=, =•.	-,
Coil resistance R at 20°C	Pump size 3	3 ÷ 3 , 3 Ω for standard 12 Vbc coil; 13 ÷ 13 , 4 Ω for 18 Vbc coil (only for version CZ, LQZ, LZQZ*)
	Pump sizes 4, 5	3,8 ÷ 4,1 Ω for standard 12 Vpc coil; 12 ÷ 12,5 Ω for 18 Vpc coil (only for version CZ, LQZ, LZQZ*)
Max solenoid current		2,6 A for standard 12 Vbc coil; 1,5 A for 18 Vbc coil (available only for version CZ, LQZ, LZQZ*)
Max power		35 Watt
Protection degree (CEI EN	I-60529)	IP65 for -CZ, LQZ and LZQZ; IP65÷67 for versions with integral electronics (see section 17)
Duty factor		Continuous rating (ED = 100%)

4 ELECTRONIC DRIVERS

Pump model		PES, PERS					
Drivers model	E-MI-AC-01F	E-MI-AS-IR	E-BM-AC	E-BM-AS-PS	E-ME-AC	E-RP-AC	E-RI-PES
Data sheet	G010	G020	G025	G030	G035	G100	G215

Note: for power supply and communication connector see section [1]

5 GENERAL NOTES

Atos proportional pumps are CE marked according to the applicable directives (e.g. Immunity/Emission EMC Directive and Low Voltage Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in table F003 and in the user manuals included in the E-SW programming software.

The electrical signals of the pump (e.g. monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, EN-892)

6 CONNECTIONS FOR CZ, LQZ, AND LZQZ(R)

	SOLENOID POWER SUPPLY CONNECTOR									
	PIN	Signal description								
1 SUPPLY		SUPPLY								
	2	SUPPLY								
	3	GND								

7 PRESSURE TRANSDUCER SELECTION (excluded option /X)

The pressure transducer type E-ATR-7 must be ordered separately (see table G465) For option X the pressure transducer is integral to the pump. Pump code: Pressure transducer code:

Pump code:	Pr
PVPC-PER(S)-*/200	E-/
PVPC-PER(S)-*/250	E-/
PVPC-PER(S)-*/280	E-/
PVPC-PER(S)-*/200/*/C	E-/
PVPC-PER(S)-*/250/*/C	E-/
PVPC-PER(S)-*/280/*/C	E-/

E-ATR-7/250
E-ATR-7/400
E-ATR-7/400
E-ATR-7/250/I
E-ATR-7/400/I
E-ATR-7/400/I

8 ELECTRONICS OPTIONS FOR PES AND PERS

Standard execution provides on the 12 pin main connector:

Power supply-The power supply must be appropriately stabilized or rectified and filtered: apply at least a 10000 μF/40 V capacitance to single
phase rectifiers or a 4700 μF/40 V capacitance to three phase rectifiers.
A safety fuse is required in series to each driver power supply: 2,5 A fuse

 Reference input signals
 -The driver controls in closed loop both the pump flow and pressure proportionally to the external reference input signals. The driver is designed to receive two analog reference input signals both referred to the common mode signal zero (AGND). The inputs range and polarity are software selectable within the ±10 Vpc maximum range; default settings are 0 ÷ +10 Vpc. Driver with fieldbus interface (-BC or -BP) can be software set to receive reference values directly by the machine control unit (fieldbus master); in this case the analog reference input signals can be used for start-up and maintenance operations.

Monitor output signals -The driver generates an analog output signals proportional to the actual pump swashplate position and to the actual pressure on the pump outlet line; the monitor output signals can be software set to show other signals available in the driver (e.g. analog reference, fieldbus reference, pilot spool position). The output polarity is software selectable within ±10 Vbc maximum range; default settings are 0 ÷ +10 Vbc.

Fault Output Signal -Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4 ÷ 20mA input, pressure/swashplate/pilot transducer cable broken, etc.). Fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC (pin 11 referred to pin2). Fault status is not affected by the status of the Enable input signal

Enable Input Signal -To enable the driver, supply a +24VDC on pin 3 referred to pin 2: when the Enable signal is set to zero the pump functioning is (only for /S and /SX options) disabled but the driver current output stage is still active. This condition does not comply with European Norms EN954-1.

For other functions, see table G215.

Following options are available to standard execution to special application requirements.

8.1 Option /I

It provides 4÷20 mA current reference and monitor signals instead of the standard 0÷+10 VDC.

It is normally used in case of long distance between the machine control unit and the pump or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.

8.2 Option /C

The pump electronics is set to receive 4÷20 mA feedback signal from the remote pressure transducer, instead of the standard 0÷10 V.

8.3 Option /X (only for -PERS)

Option providing the presence of the pressure transducer, with output signal 4÷20 mA, integral to the pump and factory wired to the PES electronics through a cable gland.

8.4 Option /S

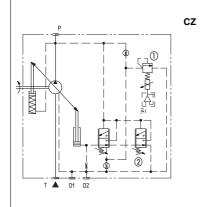
Multiple pressure PID selection (only for /S and /SX options in -PS execution)	PID SET SELECTION					
Two on-off input signals are available on the main connector to switch the active pressure	PIN	SET 1	SET 2	SET 3	SET 4	
PID parameters among one of the four setting stored into the driver.	9	0	0	24 VDC	24 VDC	
Supply a 24V or a 0V on pin 9 and/or 10, to select one of the PID settings as indicated in the table beside	10	0	24 Vpc	24 Vpc	0	

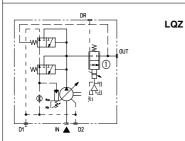
Logic power supply (only for /S and /SX options in -BC or /BP execution)

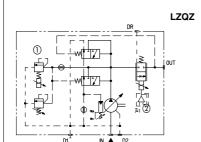
Separate power supply for the solenoid (pin 1,2) and for the digital electronic circuits (pin 9,10).

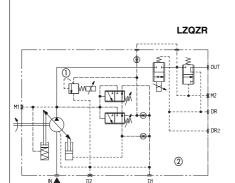
Cutting solenoid power supply allows to interrupt the valve functioning but keeping energized the digital electronics thus avoiding fault conditions of the machine fieldbus controller (e.g. for emergency, as provided by the European Norms EN954-1 for components with safety class 2). Note: pin 2 and 10 (zero Volt) are connected together inside the electronics;

9 ELECTROHYDRAULIC CONTROLS









Proportional pressure compensator

The pumps displacement, and thus the flow, remains constant as far the pressure in the circuit reaches the value set on the proportional pilot valve (1), then the flow is reduced to maintain the circuit pressure to the value set by the electronic reference signal to the proportional valve. In this conditions the pressure in the circuit can be continuosly modulated by means of the reference signal.

Proportional pressure setting range: see below pressure control diagram.

Compensator setting range 2: 20÷350 bar (315 bar for 090)

Compensator factory setting 2: 280 bar (250 bar for 090)

Proportional flow (load-sensing)

Open loop control of the flow rate via an reference signal to the electronic driver of the pilot proportional valve.

This energy saving control regulates the outlet pressure up to the minimum level required to operate the flow set by the reference signal to the proportional valve (1).

Proportional pressure & flow (load sensing)

Open loop control of pressure (1) and flow (2) via two reference signals to the electronic drivers of the two pilot proportional valves. This energy saving control regulates the outlet pressure up to the minimum level required to operate the flow set by the reference signal.

In addition the proportional pressure control reduces the outlet flow, as per CZ control once max pressure is reached.

Minimum regulated pressure: 15 bar For lower minimum regulated pressure, con-

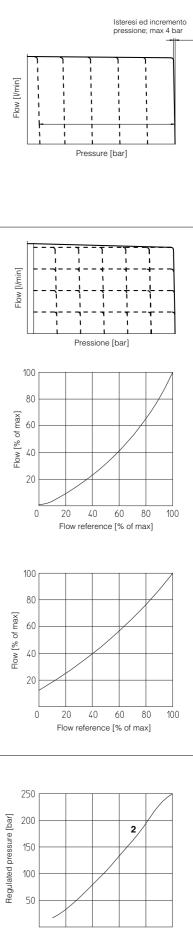
sult our technical office.

Maximum allowed pressure: 250 bar

Flow and pressure proportional control with sequence module.

Same construction concept of LZQZ control, in addition it is equipped with RES (2) sequence module which ensures the minimum pump piloting pressure in case the system pressure drops below the minimum value (18 bar).

Note: DR2 is available only for size 50.



88 73 46 29 cm3/rev 125 105 65 40 100 84 52 32 Regulated flow [I/ min] 75 63 39 24 50 42 26 16 1 25 21 13 8

> 800 1000

400 500 600

1200 1400

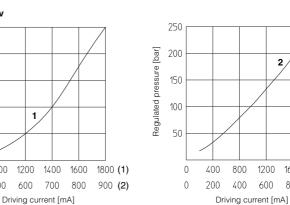
700

Pump size

Diagrams for CZ, LQZ, LZQZ

Regulation diagrams 1 = Flow control

- 2 = Pressure control
- (1) for standard 12 VDc coil (2) for 18 Vpc coil

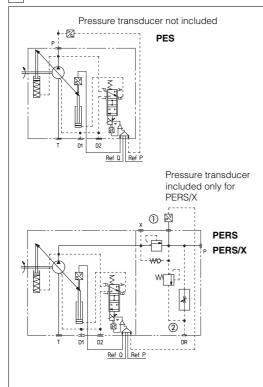


2000 (1)

1000 (2)

1600

800



Digital P/Q controller integrates the alternate pressure and flow regulation with the electronic max power limitation.

A remote pressure transducer must be installed on the system and its feedback has to be interfaced to the pump digital driver

Flow control is active when the actual system pressure is lower than the pressure reference input signal: the pump flow is regulated according to the flow reference input. Pressure control is activated when the actual pressure grows up to the pressure refe-rence input signal: the pump flow is then reduced in order to regulate and limit the max system pressure (if the pressure tends to decrease under its command value, the flow control returns active). This option allows to realize accurate dynamic pressure profiles. Following communication interfaces are available:

· -PS, Serial communication interface. The pump reference signals are provided with analog commands via the 12 pins connector

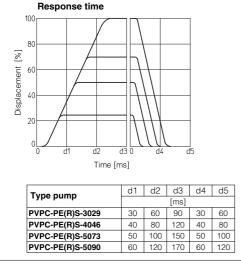
-BC, CANopen interface

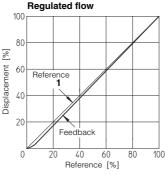
-BP, PROFIBUS DP interface

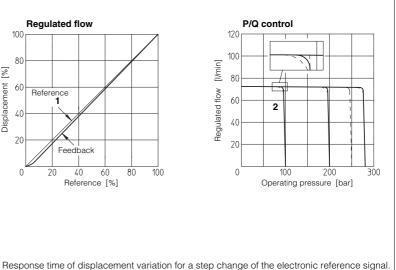
The pumps with -BC or -BP interfaces can be integrated into a fieldbus communication network and thus digitally operated by the machine control unit.

The digital control ensures high performances as flow and pressure linearity (see diagram 1), better flow knee (see diagram 2), internal leakage compensation (controlled flow independent to the load variations).

- **PVPC-PES** basic version, without sequence module and without pressure transducer, which has to be installed on the main line and wired to the 12 poles connector of the integral digital electronics.
- **PVPC-PERS** version with sequence module RES 2 which grant a minimum piloting pressure (18 bar) when the actual pressure falls below that value. Without pressure transducer.
- $\ensuremath{\text{PVPC-PERSX}}$ as -PERS version plus integral pressure transducer, with output signal 4÷20 mA, factory wired to the pump digital electronics through a cable gland.



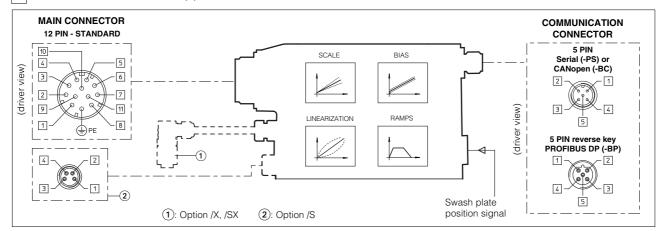




11 SOFTWARE TOOLS

The functional parameters of the digital valves, as the bias, scale, ramp and linearization of the regulation characteristic, can be easily set and optimized with graphic interface by using the Atos E-SW/S software and the relevant USB adapters, cable and terminators, see tab. G500. Valves with fieldbus communication interface (-BC and -BP) can be completely managed by the machine control unit; it is required to implement in the machine control the standard communication as described in the user manuals supplied with the relevant programming software. For detailed description of availabile fieldbus features, see tab. G510

12 DIGITAL INTEGRAL DRIVERS -PE(R)S MAIN FUNCTION AND ELECTRONICS CONNECTIONS



13 ELECTRONIC CONNECTIONS - Standard and Standard with /X option

PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES				
1	V+	Power supply 24 Vbc for pilot valve's solenoid power stage					
2	VO	Gnd - power supply					
3	FAULT	Driver status : Fault (0Vbc) or normal working (24 Vbc)	Output - on/off signal				
4	AGND	Ground : signal zero for MONITOR signals (pin 6,8) and INPUT+ signals (pin 5,7)	Gnd - analog signal				
5	Q_INPUT+	Flow reference: ±10 Vbc maximum range (4 ÷ 20 mA for /l option)	Input - analog signal				
6	Q_MONITOR	Flow monitor: ±10 Vbc maximum range (4 ÷ 20 mA for /I option)	Output - analog signal				
7	P_INPUT+	Pressure reference: ±10 Vbc maximum range (4 ÷ 20 mA for /l option)	Input - analog signal				
8	P_MONITOR	Pressure monitor: ±10 Vbc maximum range (4 ÷ 20 mA for /I option)	Output - analog signal				
9	D_IN	Power limitation enable, multiple pressure PID selection or driver enable (software selectable)	Input - on/off signal				
10	TR (1)	Remote pressure transducer feedback: 0÷10 Vpc maximum range (4 ÷ 20 mA for /C option)	Input - analog signal				
11	AGND (1)	Ground : signal zero for TR signal (pin 10)	Gnd - analog signal				
PE	EARTH	Internally connected to driver housing					

(1): Do not connect for pumps with integral pressure transducer (standard with /X option).

Note: A minimum time of 270 to 590 ms have be considered between the driver energizing with the 24 Vbc power supply and when the pump is ready to operate; during this time the current to the valve coils is switched to zero.

These connections are the same of Rexroth A10VSO axial piston pumps, model SYDFEE and SYDFEC.

14 ELECTRONIC CONNECTIONS - /S and /SX option

PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES
1	V+	Power supply 24 Vbc for pilot valve's solenoid power stage	Input - power supply
2	VO	Power supply 0 Vpc for pilot valve's solenoid power stage	Gnd - power supply
3	ENABLE	Enable (24 VDc) or disable (0 VDc) the driver	Input - on/off signal
4	Q_INPUT+	Flow reference: ±10 VDc maximum range (4 ÷ 20 mA for /I option)	Input - analog signal
5	AGND	Ground : signal zero for MONITOR signals (pin 6,8) and INPUT+ signals (pin 5,7)	Gnd - analog signal
6	Q_MONITOR	Flow monitor: ±10 Vpc maximum range (4 ÷ 20 mA for /l option)	Output - analog signal
7	P_INPUT+	Pressure reference: ±10 Voc maximum range (4 ÷ 20 mA for /l option)	Input - analog signal
8	P_MONITOR	Pressure monitor: ±10 Vbc maximum range (4 ÷ 20 mA for /l option)	Output - analog signal
11	FAULT	Driver status : Fault (0Vbc) or normal working (24 Vbc)	Output - on/off signal
PE	EARTH	Internally connected to driver housing	
PS exec	ution	·	
9	D_IN0	Multiple pressure PID selection	Input - on/off signal
10	D_IN1	Multiple pressure PID selection	Input - on/off signal
BC and	BP execution		-
9	VL+	Power supply 24 Vbc for driver's logic	Input - power supply
10	VLO	Power supply 0 Voc for driver's logic	Gnd - power supply

Note: A minimum time of 270 to 590 ms have be considered between the driver energizing with the 24 Vbc power supply and when the pump is ready to operate; during this time the current to the valve coils is switched to zero.

These connections are the same of Moog radial piston pumps, model RKP-D.

15 ELECTRONIC CONNECTIONS - 4 PIN REMOTE PRESSURE TRANSDUCER M8 CONNECTOR (only for /S option)

PIN	/S optic	on	/CS option (Ri = 316 W)			
1	TR	remote pressure trasducer feedback input ($0 \div + 10 \text{ VDC}$)	TR	remote pressure trasducer feeback (4÷20 mA)		
2	AGND	signal zero for remote transducer power supply and feedback	NC	reserved (do not connect)		
3	VT	remote transducer power supply +24 VDC	VT	remote transducer power supply +24 VDC		
4	NC	reserved (do not connect)	NC	reserved (do not connect)		

See tab. G465 for the pressure transducer characteristics and connections.

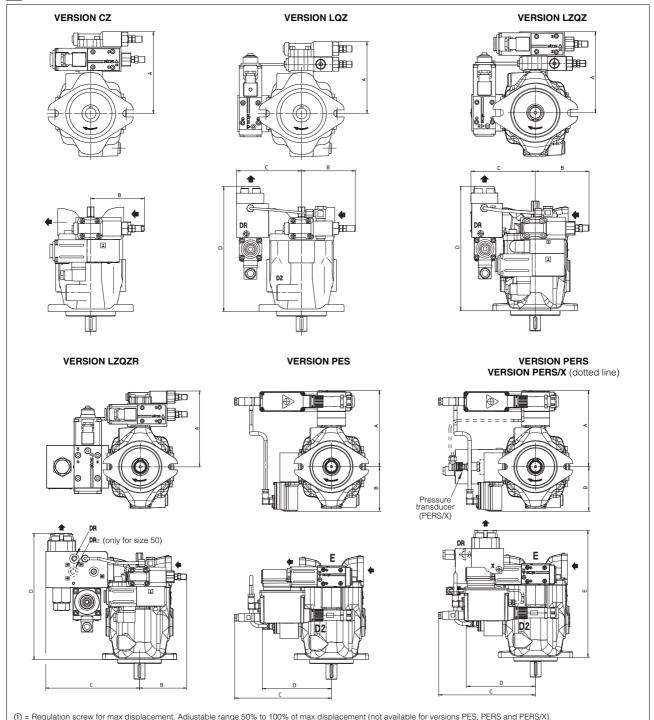
16 ELECTRONIC CONNECTIONS - 5 PIN COMMUNICATION M12 CONNECTOR

	-PS Serial		-PS Serial -BC CANopen		-BP PROFIBUS DP		
PIN	SIGNAL	TECHNICAL SPECIFICATION	SIGNAL	TECHNICAL SPECIFICATION	SIGNAL	TECHNICAL SPECIFICATION	
1	NC	do not connect	CAN_SHLD	Shield	+5V	for termination	
2	NC	do not connect	NC	do not connect	LINE-A	Bus line (high)	
3	RS_GND	Signal zero data line	CAN_GND	Signal zero data line	DGND	data line and termination Signal zero	
4	RS_RX	Valves receiving data line	CAN_H	Bus line (high)	LINE-B	Bus line (low)	
5	RS_TX	Valves transmitting data line	CAN_L	Bus line (low)	SHIELD		

17 MODEL CODE OF POWER SUPPLY AND COMMUNICATION CONNECTORS

PUMP VERSION	CZ, LQZ, LZQZ	PES, PERS	-Serial (-PS) or CANopen (-BC) only for PES and PERS	PROFIBUS DP (-BP) only for PES and PERS	PRESSURE TRANSDUCER only for /S
CONNECTOR CODE SP-666		SP-ZH-12P (1)	SP-ZH-5P (1)	SP-ZH-5P/BP (1)	SP-ZH-4P-M8 /5 (1)(2)
PROTECTION DEGREE IP65		IP65	IP67	IP67	IP67

(1) to be ordered separately (2) M8 connector moulded on cable 5 mt lenght



① = Regulation screw for max displacement. Adjustable range 50% to 100% of max displacement (not available for versions PES, PERS and PERS/X). In case of double pump the regulation screw is not always available, please contact our technical office.

Drawing shows pumps with clockwise rotation (option D): pumps with counterclockwise rotation (option S) will have inlet and outlet ports inverted and consequently also the position of the control devices.

Pump type	Version	А	В	С	D	E	Mass (kg)
PVPC-*-3029	CZ	168	111	-	-		22
	LQZ	144	111	132	257		24
	LZQZ	168	111	132	257		27,5
	LZQZR	168	111	185	185		29
PVPC-*-4046 -	CZ	177	111	-	-		28
	LQZ	153	111	156	293		33,6
	LZQZ	178	111	156	293		37,4
	LZQZR	178	111	220	296		39,5
PVPC-*-5073	CZ	190	111	-	-		36,9
	LQZ	166	111	163	328		44
PVPC-*-5090	LZQZ	190	111	163	328		47,6
	LZQZR	190	111	226	328		49,6
PVPC-*-3029	PES	170	103,5	246	155	-	21,6
	PERS	170	103,5	246	155	262,5	26
	PERS/X	190	103,5	246	226	262,5	26,4
PVPC-*-4046	PES	178	103,5	246	162	-	27,6
	PERS	178	103,5	246	162	299	33,7
	PERS/X	178	103,5	246	162	299	34,1
PVPC-*-5073 PVPC-*-5090	PES	190	103,5	246	171	-	36,6
	PERS	190	103,5	246	171	337	46,7
	PERS/X	190	103,5	246	171	337	47,1