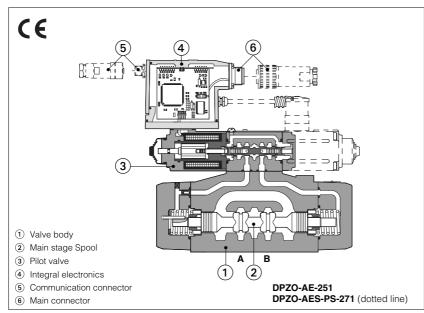


## Proportional directional valves type DPZO-A\*

two stage without position transducer, ISO 4401 sizes 10, 16 and 25



1 MODEL CODE **DPZO** - AES- PS - 2 7 1 - D Piloted proportional nthetic fluids: WG = water-glycol
PE = phosph. ester PF A = without position transduce AE = as A plus integral electroni AES = as A plus integral digital electronics AEG = as A plus integral digital cycle generator (1) Coils voltage (only for -A execution): see section 6: = standard 12 Vpc coil Communication interfaces = with 6 V<sub>DC</sub> coil (only for AES and AEG) = with 18 Vp PS = Serial BC = CANopen (only for AES)
BP = PROFIBUS DP (only for AES) Hydraulic options, see section [4]: B = solenoid and integral electronics at Valve size: side of port B of the main stage; **2** = 16 **3** = 25 D = internal drain **1** = 10 E = external pilot G = pressure reducing valve for piloting Configuration, see section 3: Electronics options for -AE execution. 5 = external plus central position, spring centered see section 8: 7 = 3 positions; spring centered

DPZO-A\* are two stage proportional valves without position transducer, which provide both directional and non compensated flow control according to the electronic reference signal.

They operate in association with electronic drivers, see section 2, which supply the proportional valves with correct current signal to align valve regulation to the reference signal supplied to the electronic

They are available in different executions:

- -A, without position transducer;
- · -AE, -AES as -A plus analogue (AE) or digital (AES) integral electronics (4).
- -AEG, as A plus integral digital cycle generator (see table G120).

The 4-way spool (2), sliding into a 5chambers body ①, is piloted in open loop by the proportional pressure reducing valve 3 type DHRZO.

The integral electronics 4 ensures factory presetting, fine functionality plus valve-tovalve interchangeability and simplified wiring and installation.

The electronic main connector (6) is fully interchangeable for -AE and -AES executions.

Standard 7 pin main connector is used for power supply, analog input reference and monitor signals.

12 pin connector is used for AEG version and for option /Z (AES).

Following communication interfaces (5) are available for the digital -AES and -AEG executions:

- -PS, RS232 serial communication interface. The valve reference signal is provided with analogue commands via the 7 (or 12) pins connector (6)
- -BC, CANopen interface (only for -AES)
- BP, PROFIBUS DP interface (only for -AES)

The valves with -BC and -BP interfaces can be integrated into a fieldbus communication network and thus digitally operated by the machine control unit.

The coils are fully plastic encapsulated (insulation class H) and valves have antivibration, antishock and weather-proof

Surface mounting: ISO 4401 size 10, 16 and 25.

Max flow respectively up to 160 l/min, 340 I/min and 680 I/min with valve differential pressure  $\Delta p = 30$  bar, see section 3.

Max pressure: 350 bar.

## L = linear **S** = progressive **D** = as **S**, but with P-A = Q, P-B = Q/2

Spool type

(1) For detailed description of AEG integral cycle generator, see table G120 (2) Overlapping = 20% of spool stroke for type **S** and **D**, 10% of spool stroke for type **L** 

#### 2 ELECTRONIC DRIVERS FOR DPZO-A\*

Spool overlapping in central position, see section 3 1 = P, A, B, T positive overlapping (2)
3 = P positive overlapping (2); A, B, T negative overlapping

Valve model	-A						-AE	-AES	-AEG
Drivers model	E-MI-AC-0*F	E-MI-AS-IR	E-BM-AC-0*F	E-BM-AS-PS	E-ME-AC-0*F	E-RP-AC-0*F	E-RI-AE	E-RI-AES	E-RI-AEG
Data sheet	G010	G020	G025	G030	G035	G100	G110	G115	G120

I = current reference input (4÷20 mA)

Electronics options for -AES execution.

I = current reference input (4÷20 mA)

Z = double power supply, enable and

fault (12 pins connector)

Q = enable signal

Spool size: 3, 5 and 9 = see section 3

see section 10

Note: For power supply and communication connector see section [17]

#### 3 HYDRAULIC CHARACTERISTICS (based on mineral oil ISO VG 46 at 50 °C)

Hydraulic symbols *71			*73		*51		*53		*51/B		*53/B
a B T b	a	A B V	b W	A B T T T T T T T T T T T T T T T T T T	Δ. Λ b	A B T	b	a	A B T T	a	A B N
Valve model		DPZO-1				DPZO-2				DPZO-3	
Spool overlapping		1, 3				1, 3				1, 3	
Spool type and size	L5	S5	D5	S3	D3	L5	S5	D5	L5	S5	D5
Max flow (1) [l/min]											
at $\Delta p = 10$ bar	100	100	100 : 60	130	130 : 80	200	180	180 : 130	390	360	360 : 220
at $\Delta p = 30$ bar	160	160	160 : 100	225	225 : 135	340	310	310 : 225	680	620	620 : 380
max permissible flow	180	180	180 : 110	500	500 : 300	710	640	640 : 460	1350	1250	1250 : 760
Pressure limits [bar]		•	р	orts P, A, I	B, X = 350;	T = 250 (	5 for optio	n /D); Y =	5		
Response time [ms]	< 80			< 100					< 120		
Hysteresis [%]		≤5%									
Repeatability						± 1%					

#### Notes:

- Above performance data refer to valves coupled with Atos electronic drivers, see section 2
- In case of long time shutdown of the hydraulic supply to the pilot valve, the driver has to be switched off to avoid its overheating.
- The flow regulated by the directional proportional valves is not pressure compensated, thus it is affected by the load variations. To keep costant the
  regulated flow under different load conditions, modular pressure compensators are available (see tab. D150).
- (1) For different  $\Delta p$ , the max flow is in accordance to the diagrams in section 14.2

#### 4 HYDRAULIC OPTIONS

- **4.1 Option /B** Solenoid (for valve configuration \*5\*) and integral electronics at side of port A.
- 4.2 Pilot and drain configuration -The pilot / drain configuration can be modified as shown in the table E080 section 12.

The valve's standard configuration provides internal pilot and external drain. For different pilot / drain configuration select:

**Option /E** External pilot (through port X). **Option /D** Internal drain.

Option /G Pressure reducing valve with fixed setting (= 40 bar for DPZO-1 and -2; 100 bar for DPZO-3) installed between pilot valve and main body. It is advisable for valves with internal pilot in case of system pressure higher than 200 bar. This option is standard for DPZO-1\*-1.

#### 5 GENERAL NOTES

DPZO-A\* proportional valves are CE marked according to the applicable Directives (e.g. Immunity/Emission EMC Directive and Low Voltage Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in table F003 and in the installation notes supplied with relevant components.

The electrical signals of the valve (e.g. monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, EN-982).

### 6 OPTIONS FOR -A EXECUTION

6.1 Option /6 6 Vpc coil instead of standard 12 Vpc, to be used in case of power supply 12 Vpc

6.2 Option /18 18 Vpc coil instead of standard 12 Vpc, to be used with electronic drivers not supplied by Atos

#### 7 CONNECTIONS FOR -A EXECUTION

SOLENOID POWER SUPPLY CONNECTOR								
PIN	Signal description							
1	SUPPLY	2 - 3						
2	SUPPLY							
3	GND							

#### 8 ANALOG INTEGRAL DRIVERS -AE - OPTIONS

Standard driver execution provides on the 7 pin main connector:

Power supply
 24Vpc must be appropriately stabilized or rectified and filtered; a 2,5 A safety fuse is required in series to the driver power supply.
 Apply at least a 10000 μF/40 V capacitance to single phase rectifiers or a 4700 μF/40 V capacitance to three phase rectifiers

Reference input signal - analog differential input with ±10 Vpc nominal range (pin D,E), proportional to desired coil current.

Monitor output signal - analog output signal proportional to the actual valve's coil current (1V monitor = 1A coil current)

Following options are available to adapt standard execution to special application requirements:

#### 8.1 Option /I

It provides the 4÷20 mA current reference signal instead of the standard ±10 Vpc. Monitor output signal is still the standard ±10 Vpc.

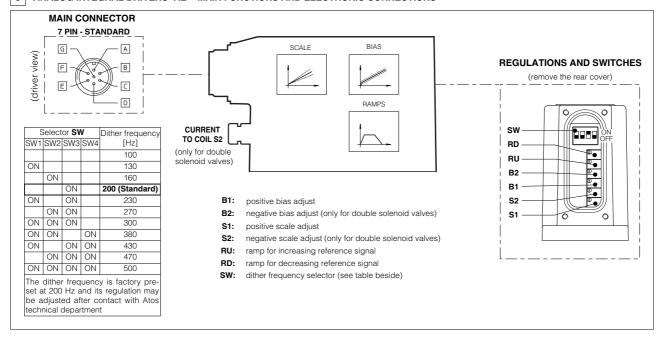
It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.

#### 8.2 Option /Q

It provides the possibility to enable or disable the valve functioning without cutting the power supply (the valve functioning is disabled but the driver current output stage is still active). To enable the driver supply a 24Vpc on the enable input signal.

#### 8.3 Possible combined options: /IQ

#### 9 ANALOG INTEGRAL DRIVERS -AE - MAIN FUNCTIONS AND ELECTRONIC CONNECTIONS



#### 9.1 ELECTRONIC CONNECTIONS - 7 PIN MAIN CONNECTORS

PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES		
А	A V+ Power supply 24 Vpc for solenoid power stage and driver logic				
В	V0	Power supply 0 VDC for solenoid power stage and driver logic	Gnd - power supply		
C (1)	AGND	Ground - signal zero for MONITOR signal		Gnd - analog signal	
	ENABLE	Enable (24 VDC) or disable (0 VDC) the driver	(for /Q option)	Input - on/off signal	
D	INPUT+	Reference analog differential input: ±10 Vpc maximum range For single solenoid valves the reference input is 0÷+10 Vpc	(4 ÷ 20 mA for /I option) (4 ÷ 20 mA for /I option)	Input - analog signal	
E INPUT -		For double solenoid valves the reference input is ±10 VDC	Imput analog dignar		
F	F MONITOR Monitor analog output: ±10 Vpc maximum range				
G	EARTH	Internally connected to the driver housing			

Note: (1) with /Q option ENABLE signal replaces AGND on pin C; MONITOR signal is reffered to pin B.

A minimum time of 60ms to 160ms have be considered between the driver energizing with the 24 Vpc power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero

#### 10 DIGITAL INTEGRAL DRIVERS -AES - OPTIONS

Standard driver execution provides on the 7 pin main connector:

Power supply
 24Voc must be appropriately stabilized or rectified and filtered; a 2,5 A safety fuse is required in series to each driver power supply
 Apply at least a 10000 μF/40 V capacitance to single phase rectifiers or a 4700 μF/40 V capacitance to three phase rectifiers.

Reference input signal - analog differential input with ±10Vpc nominal range (pin D,E), proportional to desired coil current.

Monitor output signal - analog output signal proportional to the actual valve's coil current (1V monitor = 1A coil current)

Following options are available to adapt standard execution to special application requirements:

#### 10.1 Option /I

It provides 4÷20 mA current reference signal instead of the standard ±10 Vpc. Monitor output signal is still the standard 0÷10 Vpc.

It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.

#### 10.2 Option /Z

It provides on a 12 pin main connector the above standard features plus:

#### Logic power supply

Option /Z provides separate power supply for the solenoid (pin 1, 2) and for the digital electronic circuits (pin 9, 10).

Cutting solenoid power supply allows to interrupt the valve functioning but keeping energized the digital electronics thus avoiding fault conditions of the machine fieldbus controller. This condition allows to realize safety systems in compliance with European Norms EN13849-1 (ex EN954-1).

#### **Enable Input Signal**

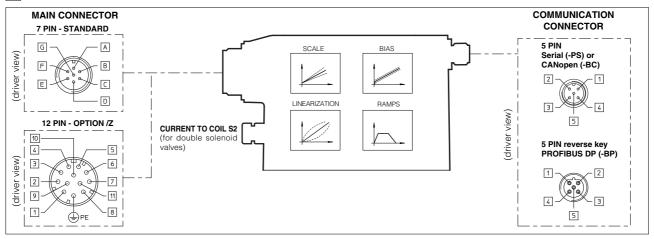
To enable the driver, supply a 24Vpc on pin 3 referred to pin 2: when the Enable signal is set to zero the valve functioning is disabled (zero current to the solenoid) but the driver current output stage is still active. This condition does not comply with European Norms EN13849-1 (ex EN954-1).

#### Fault Output Signal

Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4÷20mA input, etc.). Fault presence corresponds to 0 Vpc, normal working corresponds to 24Vpc (pin 11 referred to pin 2): Fault status is not affected by the Enable input signal

#### 10.3 Possible combined options: $\ensuremath{\text{IZ}}$

#### 11 DIGITAL INTEGRAL DRIVERS -AES - MAIN FUNCTIONS AND ELECTRONIC CONNECTIONS



#### 11.1 ELECTRONIC CONNECTIONS - 7 & 12 PIN MAIN CONNECTORS

Standard 7pin	/Z option 12pin	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES
А	1	V+	Power supply 24 Vpc for solenoid power stage (and for driver logic on 7 pin connection)	Input - power supply
В	2	V0	Power supply 0 Vpc for solenoid power stage (and for driver logic on 7 pin connection)	Gnd - power supply
-	3	ENABLE	Enable (24 Vpc) or disable (0 Vpc) the driver	Input - on/off signal
D	4	INPUT+	Reference analog input: ±10 Vpc maximum range (4 ÷ 20 mA for /l option)	
Е	-	INPUT -	For single solenoid valves the reference input is 0÷+10 Vpc (4 ÷ 20 mA for /I option) For double solenoid valves the reference input is ±10 Vpc (4 ÷ 20 mA for /I option) standard: differential input; /Z option: common mode INPUT+ referred to AGND	Input - analog signal
С	5	AGND	Ground - signal zero for MONITOR signal signal zero for INPUT+ signal (only for /Z option)	Gnd - analog signal
F	6	MONITOR	Monitor analog output: ±10 Vpc maximum range	Output - analog signal
-	7	NC	do not connect	
-	8	NC	do not connect	
-	9	VL+	Power supply 24 Vpc for driver logic	Input - power supply
-	10	VL0	Power supply 0 Vpc for driver logic	Gnd - power supply
-	11	FAULT	Fault (0 VDC) or normal working (24 VDC)	Output - on/off signal
G	PE	EARTH	Internally connected to the driver housing	

A minimum time of 270 to 340 ms have be considered between the driver energizing with the 24 VDC power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero

#### 11.2 ELECTRONIC CONNECTIONS - 5 PIN COMMUNICATION CONNECTORS

	-PS Serial		-BC CANopen			-BP PROFIBUS DP		
PIN	SIGNAL	TECHNICAL SPECIFICATION	SIGNAL	TECHNICAL SPECIFICATION	SIGNAL	TECHNICAL SPECIFICATION		
1	NC	do not connect	CAN_SHLD	Shield	+5V	for termination		
2	NC	do not connect	NC	do not connect	LINE-A	Bus line (high)		
3	RS_GND	Signal zero data line	CAN_GND	Signal zero data line	DGND	data line and termination Signal zero		
4	RS_RX	Valves receiving data line	CAN_H	Bus line (high)	LINE-B	Bus line (low)		
5	RS_TX	Valves transmitting data line	CAN_L	Bus line (low)	SHIELD			

#### 12 SOFTWARE TOOLS

The functional parameters of digital valves, as the bias, scale ramp and linearization of the regulation characteristic, can be easily set and optimized with the Atos E-SW programming software, available in three different versions according to the driver's communication interfacing: E-SW-PS (Serial), E-SW-BC (CANopen) and E-SW-BP (PROFIBUS DP).

A proper connection is required between the PC and the electronic driver communication port: for a more detailed description of software interface, PC requirements, adapters, cables and terminators, please **see table G500**.

Proportional valves with fieldbus communication interface (-BC and -BP) can be directly managed by the machine control unit; it is required to implement in the machine control the standard communication as described in the user manuals supplied with the relevant programming software. For detailed description of available fieldbus feature, **see table G510**. description of available fieldbus feature, see table G510.

On first supply of the E-SW software, it is required to apply for the registration in the Atos download area: www.download.atos.com

Once the registration is completed, the password will be sent by email.

The software remains active for 10 days from the installation date and then it stops until the user inputs his password.

With the password you can also download, in your personal area, the latest releases of the Atos software, manuals, drivers and configuration files.

#### 13 MAIN CHARACTERISTICS OF PROPORTIONAL DIRECTIONAL VALVES TYPE DPZO-A\*

Assembly position	Any position	Any position					
Subplate surface finishing	Roughness index, $\sqrt{0.4}$ flatness ra	Roughness index, $\sqrt{\frac{0.4}{100}}$ flatness ratio 0,01/100 (ISO 1101)					
Ambient temperature	-20°C ÷ +70°C for -A execution; -2	20°C ÷ +60°C for -AE and -AES exec	utions				
Fluid	Hydraulic oil as per DIN 51524	535 for other fluids see section 1					
Recommended viscosity	15 ÷100 mm²/s at 40°C (ISO VG 18	15 ÷100 mm²/s at 40°C (ISO VG 15÷100)					
Fluid contamination class	ISO 18/15 achieved with in line filte	ISO 18/15 achieved with in line filters of 10 μm and β10≥75 (recommended)					
Fluid temperature	-20°C +60°C (standard and /WG s	-20°C +60°C (standard and /WG seals) -20°C +80°C (/PE seals)					
Coil voltage	12 V∞ coil	6 V∞ coil	18 V₀c coil				
Coil resistance R at 20°C	3 ÷ 3,3 Ω	2 ÷ 2,2 Ω	13 ÷ 13,4 Ω				
Max. solenoid current	1,9 A	1,9 A 2,35 A 0,9 A					
Max. power		30 Watt					
Protection degree (CEI EN-60529)	IP65 for -A execution; IP65÷67 for -A	IP65 for -A execution; IP65÷67 for -AE and -AES executions, depending to the connector type, see sect. [7]					
Relative duty factor	Continuous rating (ED=100%)	Continuous rating (ED=100%)					

## 14 DIAGRAMS (based on mineral oil ISO VG 46 at 50 °C)

#### 14.1 Regulation diagrams

DPZO-1:

1 = linear spool 2 = differential spool S5, D5

3 = progressive spool S3, D3 4 = progressive spool S5, D5 5 = linear spool L5

DPZO-3:

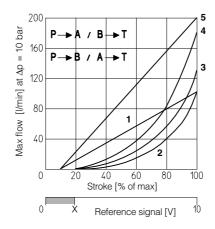
6 = linear spool L5 7 = progressive spool S5, D5

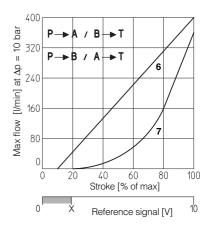
#### Note:

Hydraulic configuration vs. reference signal: for double solenoid valves (also for option /B)

0 ÷+10 V 12÷20 mA Reference signal  $P \rightarrow A / B \rightarrow T$ 

 $\begin{array}{cc} 0 \div -10 \text{ V} \\ 4 \div 12 \text{ mA} \end{array}$  P  $\rightarrow$  B / A  $\rightarrow$  T Reference signal





 $\mathbf{X}$  = Threshold for bias activation depending to the valve type and amplifier type

#### 14.2 Flow /∆p diagram

Stated at 100% of valve stroke

DPZO-1:

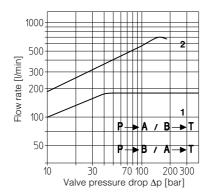
1 = spool L5, S5, D5

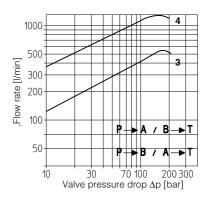
DPZO-2:

2 = spool L5, S5, D5 3 = spool S3, D3

DPZO-3:

4 = spool L5, S5, D5

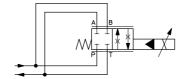




#### 14.3 Operation as throttle valve

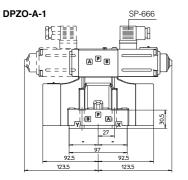
Single solenoid valves (\*51) can be used as simple throttle valves: Pmax = 250 bar

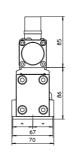
For this application, the use of valve -T, -TE or -TES (see tab. F172 and F175) is advisable (consult our technical office)



DPZO	_*_	151-L5	251-L5	351-L5		
Max flow	[l/min]	320	650	1300		
Δр	[bar]	30	30	30		

## **DPZO-A(\*)-1** (dotted line = double solenoid version)





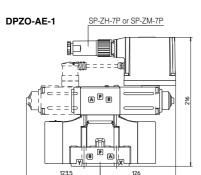
#### ISO 4401: 2005

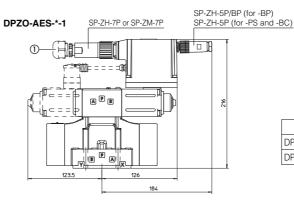
Mounting surface: 4401-05-05-0-05 (see table P005)

Fastening bolts:

4 socket head screws M6x40 class 12.9 Tightening torque = 15 Nm Seals: 5 OR 2050; 2 OR 108 Diameter of ports A, B, P, T: Ø = 11 mm;

Diameter of ports X, Y:  $\emptyset = 5$  mm;





# Mass [kg] A AE, AES DPZO-\*-15\* 7,7 8,1 DPZO-\*-17\* 8,6 9,1

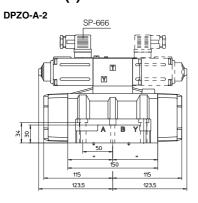
#### -AES EXECUTION

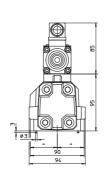
1 = 12 pin connector SP-ZH-12P for option /Z

#### NOTE:

For option /B the proportional solenoid and the electronics (in case of execution -AE and -AES) are at side of port B of the main stage.

## **DPZO-A(\*)-2** (dotted line = double solenoid version)





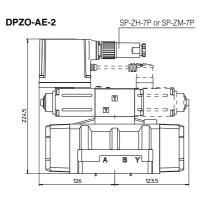
#### ISO 4401: 2005

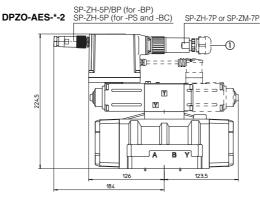
Mounting surface: 4401-07-07-0-05 (see table P005)

Fastening bolts:

4 socket head screws M10x50 class 12.9 Tightening torque = 70 Nm 2 socket head screws M6x40 class 12.9 Tightening torque = 15 Nm Seals: 4 OR 130; 3 OR 109/70

Diameter of ports A, B, P, T:  $\emptyset$  = 20 mm; Diameter of ports X, Y:  $\emptyset$  = 7 mm;





Mass [kg]							
	Α	AE, AES					
DPZO-*-25*	11,9	12,3					
DPZO-*-27*	12,8	13,3					

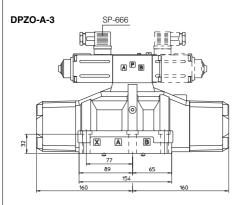
#### -AES EXECUTION

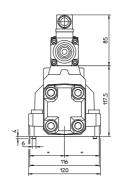
1 = 12 pin connector SP-ZH-12P for option /Z

#### NOTE

For option /B the proportional solenoid and the electronics (in case of execution -AE and -AES) are at side of port B of the main stage.

## **DPZO-A(\*)-3** (dotted line = double solenoid version)





#### ISO 4401: 2005

Mounting surface: 4401-08-08-0-05 (see table P005)

Fastening bolts:

6 socket head screws M12x50 class 12.9

Tightening torque = 125 Nm

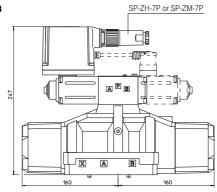
Seals: 4 OR 4112; 3 OR 3056

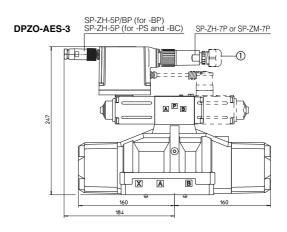
Diameter of ports A, B, P, T:  $\emptyset$  = 24 mm; Diameter of ports X, Y:  $\emptyset$  = 7 mm;

Mass [kg]

	Α	AE, AES
DPZO-*-35*	17,1	17,5
DPZO-*-37*	18	18,4







#### -AES EXECUTION

① = 12 pin connector SP-ZH-12P for option /Z

#### NOTE:

For option /B the proportional solenoid and the electronics (in case of execution -AE and -AES) are at side of port B of the main stage.

#### 17 MODEL CODES OF POWER SUPPLY AND COMMUNICATION CONNECTORS (to be ordered separately)

VALVE VERSION	-A	-AE,	-AES	-AES/Z -AEG	-Serial (-PS) or CANopen (-BC)	PROFIBUS DP (-BP)
CONNECTOR CODE	SP-666	SP-ZH-7P	SP-ZM-7P	SP-ZH-12P	SP-ZH-5P	SP-ZH-5P/BP
PROTECTION DEGREE	IP65	IP67	IP67	IP65	IP67	IP67
DATA SHEET	K500		G110, G115, K500		G115	, K500

connectors supplyed with the valve