

Digital servoactuators for PARISON controls

in blow molding machines



060810	CKZ - X	L - NN - 1	0 - 80/36	*0012 -	· A -	PS /	GP	* /	/ *
Mounting flange with threaded holes									Rod position vs. position signal: - = fully in at 0 V _{DC}
Servoactuator type:									B = fully out at 0 VDC
CKZ = ISO 6020-2								Powe	r supply connector
Control type: \mathbf{X} = position	n/speed							- Z	= 7 pin = 12 pin
Position/speed transducer	r type: L = LVDT						Pariso	on contr	ol
						RS232	2 serial	commu	nication interface
No pressure/force control	and no pressure/for	ce transducer			_				
Proportional value size					Front fl	lange a	ttachm	ent	
1 = size 06 (only for cyli 2 = size 10 (only for cyli	inder size 63/28, 80/36 inder size 160/70 and 2	, 100/45) 200/90)		Stroke = 1	12 mm				
Subplate type: 0 = standa	ard		Piston/ro 63/28	d size [mm] 80/36 100	(1) 0/45 12	25/45	160/70	0 200	/90

63/28 80/36 100/45 125/45 160/70

2 SERVOACTUATOR COMPOSITION

Servoactuator model code	Servocylinder code	Servoproportional pilot valve code (see tab. F180)	
060810 CKZ-XL-NN-10-63/28*0012-A-PS/GP	07K0323 CKT/10-9-63/28*0012-A002-L-B1X1		
060810 CKZ-XL-NN-10-80/36*0012-A-PS/GP	02K1260 CKT/10-9-80/36*0012-A002-L-B1X1		
060810 CKZ-XL-NN-10-100/45*0012-A-PS/GP	06K0120 CKT/10-9-100/45*0012-A002-L-B1X1	050321 DEHZO-1EZ-LIN-F3-040-L51/B	
060810 CKZ-XL-NN-10-125/45*0012-A-PS/GP	06K0122 CKT/10-9-125/45*0012-A002-L-B1X1		
060810 CKZ-XL-NN-20-160/70*0012-A-PS/GP	06K0219 CKT/20-9-160/70*0012-A002-L-B1X1		
060810 CKZ-XL-NN-20-200/90*0012-A-PS/GP	08K0125 CKT/20-9-200/90*0012-A002-L-B1X1	000200 DLNZOR-TEZ-LIN-P'S-140-L31/B	

Description:

The Parison control is a well known process used in the plastic blow molding machines for the wall thickness distribution of continuous extruded profiles.

It is mainly used to obtain hollow items, as plastic bottles, tanks, etc, whose thickness can be modulated depending to the requi-red localized mechanical resistance. The wall thickness is realized by means of a spe-cific servoactuator operated in position clo-sed loop control (see below the application papera) scheme)

scneme). The Atos servoactuators CKZ are special pro-portional servo cylinders with digital integral position control, providing high performances and high regulation repeatability. The integral and compact execution ensures the best stiffness of the hydraulic system and it permits high dynamics and position accuracy.

Characteristics:

- The digital servoactuator is composed by: Special cylinder equipped with low friction seals and with LVDT position transducer. The rod end is threaded for the connection
- High dynamic proportional valve with zero lapped spool and LVDT position transducer
 Digital integral electronics with double position closed loop control of pilot valve and of cylinder rod. The RS232 serial communication interface permits to optimize the application's performance. the application's performances, modifying via software, the internal parameters by means of the relevant programming device KIT-E-SW-PS to be used with standard PC

The servoactuator is operated by means of analog commands sent to the 7 or 12 pins

power supply connector. The command signal 0+10 VDc defines the servocylinder rod position in the stroke range 0-12 mm.

The default condition is 0 VDC = rod position fully in; 10 VDC = rod position 12 mm Available sizes: ø63/28, ø80/36, ø100/45, ø125/45 ø160/70, ø200/90 mm. Stroke: 12 mm.

3 MAIN CHARACTERISTICS

Bore diameter		[mm]	63	80	100	125	160	200
Rod diameter		[mm]	28	36	45	45	70	90
Working stroke [mm]			12					
Max pressure [bar]			160					
May force	(kN)	Pull	40	64	100	170	260	400
Max Iorce		Push	50	80	125	190	320	500
Max speed [m/s]			0,5					
Command signal [VDC]			0÷10 (0V = rod fully in: standard) (0V = rod fully out: option /B)					
Linearity			0,03 %					
Response time at step signal (0-100%) [ms]			85	115	300	320	30	00

4 INTEGRAL DIGITAL ELECTRONICS WIRING



POWER SUPPLY CONNECTOR (front view)



12 PIN POWER SUPPLY CONNECTOR - OPTION /Z (front view)

	POWER SUPP	LY CONNECTOR (STANDARD)	POWER SUPPLY CONNECTOR (OPTION /Z)				
PIN	SIGNAL DESCRIPTION	TECHNICAL SPECIFICATION		SIGNAL DESCRIPTION	TECHNICAL SPECIFICATION		
A	Power supply 24 VDC	Stabilized: +24Vbc	1	Power supply 24 Vbc (power stage)	Stabilized:	+24 VDC	
В	Power supply zero	Filtered and rectified: $V_{rms} = 21 \div 33$ (ripple max $2V_{pp}$)	2	Power supply 0 Voc (power stage)	Filtered and rectified:	Vrms 21-33 (ripple max 2 Vpp)	
С	Signal zero	Reference 0 VDC	3	Enable	Enabling input norm	al working 24 Vbc	
D	Input signal +	0 - 10 Voz		Input signal +	D ÷10 VDC		
Е	Input signal -		5	Signal zero	Reference signal 0 VDC		
F	Monitor (Red position)	0 ÷ 10 V		Monitor (rod position)	1V = 10% of rod position (referred to pin 5)		
	Nonitor (Rod position)	1 V = 10% of cylinder stroke	7	NC	Not connected		
G	Farth	Connect only when the power supply is not	8	NC	Not connected		
	Latur	conform to VDE 0551 (CEI 14/6)	9	Power supply 24 Vbc (logic stage)	Stabilized:	+24 VDC	
			10	Power supply 0 Vbc (logic stage)	Filtered and rectified:	Vrms 21-33 (ripple max 2 Vpp)	
			11	Fault	Alarm = 0 Voc	Correct functioning = +24 Vpc	
			PE	Earth	Connect only when	the power supply is not	
					conform to VDE 055	1 (CEI 14/6)	

	со	MMUNICATION CONNECTOR	
Commur optio	iication ns	PS (RS232) male connector	
		NC	
		Not Connected	2
n number Il description		NC	
	2	Not Connected	
	3	RS_GND	
		Signal zero data line	5
jgna	4	RS_RX	COMMUNICATION
0, 4	4	Valves receiving data line	(front view)
	5	RS_TX	
		Valves transmitting data line	

5	MODEL CODE of power supply and communication connectors
	(to be ordered separately)

POWER SUPPLY CONNECTOR	COMMUNICATION CONNECTOR			
SP-ZH-7P	SD 7H 5D			
SP-ZH-12P (option /Z)	3F-2H-3F			

6 PROGRAMMING DEVICES

The functional parameters of the servoactuator, as the bias, scale, ramp and linearization of the regulation characteristic, can be easily set and optimized with graphic interface by using the following software programming devices suitable for standard PC:

KIT-E-SW-PS for electronics with RS232 interface (option -PS) see tab. G500 for complete information about the programming device kits and for the PC minimum requirements.

The above programming devices have to be ordered separately.









060810 CKZ-XL-NN-10-80/36*0012-A-PS-GP







060810 CKZ-XL-NN-10-100/45*0012-A-PS-GP



Mass: 36 kg





060810 CKZ-XL-NN-10-125/45*0012-A-PS-GP







Mass: 53 kg

060810 CKZ-XL-NN-20-160/70*0012-A-PS-GP







060810 CKZ-XL-NN-20-200/90*0012-A-PS-GP

