

2 GENERAL NOTES

Atos digital proportional valves are CE marked according to the applicable directives (e.g. Immunity and Emission EMC Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in tech table **FX900** and in the user manuals included in the E-SW-SETUP programming software.

3 VALVE SETTINGS AND PROGRAMMING TOOLS - see tech. table **GS500**

WARNING: the below operation must be performed in a safety area!

3.1 Atos CONNECT mobile App

Free downloadable App for smartphones and tablets which allows quick access to valve main functional parameters and basic diagnostic information via Bluetooth, thus avoiding physical cable connection and significantly reducing commissioning time. Atos CONNECT supports Atos digital valve drivers equipped with E-A-BTH adapter or with built-in Bluetooth. It does not support valves with p/Q control or axis controls.



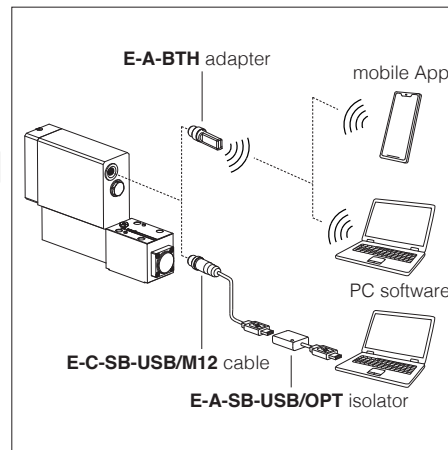
3.2 E-SW-SETUP PC software

Free downloadable software for PC allows to set all valve functional parameters and to access complete diagnostic information of digital valve drivers via Bluetooth/USB service port. Atos E-SW-SETUP PC software supports all Atos digital valve drivers and it is available at www.atos.com in MyAtos area.

WARNING: drivers USB port is not isolated! For E-C-SB-USB/M12 cable, the use of E-A-SB-USB/OPT isolator adapter is highly recommended for PC protection

WARNING: for the list of countries where the Bluetooth adapter has been approved, see tech. table **GS500**

Bluetooth or USB connection



4 FIELDBUS - see tech. table **GS510**

Fieldbus allows valve direct communication with machine control unit for digital reference, valve diagnostics and settings. These executions allow to operate the valves through fieldbus or analog signals available on the terminal board.

5 GENERAL CHARACTERISTICS

Assembly position	Any position
Subplate surface finishing to ISO 4401	Acceptable roughness index, $R_a \leq 0,8$ recommended $R_a 0,4$ - flatness ratio 0,01/100
MTTFd values according to EN ISO 13849	75 years, for further details see technical table P007
Ambient temperature range	Standard = $-20^\circ\text{C} \div +60^\circ\text{C}$ / PE option = $-20^\circ\text{C} \div +60^\circ\text{C}$ / BT option = $-40^\circ\text{C} \div +60^\circ\text{C}$
Storage temperature range	Standard = $-20^\circ\text{C} \div +70^\circ\text{C}$ / PE option = $-20^\circ\text{C} \div +70^\circ\text{C}$ / BT option = $-40^\circ\text{C} \div +70^\circ\text{C}$
Surface protection	Zinc coating with black passivation
Corrosion resistance	Salt spray test (ISO 9227) > 200 h
Vibration resistance	See technical table GX004
Compliance	Explosion proof protection, see section 9 -Flame proof enclosure "Ex d" -Dust ignition protection by enclosure "Ex t" RoHs Directive 2011/65/EU as last update by 2015/863/EU REACH Regulation (EC) n°1907/2006

6 HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Valve model	DPZA-*-1	DPZA-*-2	DPZA-*-4	DPZA-*-6		
Pressure limits [bar]	ports P, A, B, X = 350; T = 250 (10 for option /D); Y = 10;					
Spool type and size	L5, S5, D5	L3, S3, D3	L5, S5, D5			
Nominal flow [l/min]						
Δp P-T	$\Delta p = 10$ bar	100	160	250	480	640
	$\Delta p = 30$ bar	160	270	430	830	1100
Max permissible flow	180	400	550	900	1500	
Δp max P-T [bar]	50	60	60	60	60	
Piloting pressure [bar]	min. = 25; max = 350 (option /G advisable for pilot pressure > 150 bar)					
Piloting volume [cm³]	1,4	3,7		9,0	21,6	
Piloting flow (1) [l/min]	1,7	3,7		6,8	14,4	
Leakage (2) Main stage [l/min]	0,15/0,5	0,2/0,6		0,3/1,0	1,0/3,0	
Response time (1) [ms]	≤ 90	≤ 110		≤ 130	≤ 190	
Hysteresis	≤ 5 [% of max regulation]					
Repeatability	± 1 [% of max regulation]					

(1) 0 ÷ 100 % step signal and pilot pressure 100 bar
(2) at $p = 100/350$ bar


7 ELECTRICAL CHARACTERISTICS

Power supplies	Nominal : +24 VDC Rectified and filtered : VRMS = 20 ÷ 32 VMAX (ripple max 10 % VPP)			
Max power consumption	35 W			
Analog input signals	Voltage: range ±10 VDC (24 VMAX tolerant) Current: range ±20 mA		Input impedance: Ri > 50 kΩ Input impedance: Ri = 500 Ω	
Insulation class	H (180°) Due to the occurring surface temperatures of the solenoid coils, the European standards ISO 13732-1 and EN982 must be taken into account			
Monitor outputs	Voltage: maximum range ± 5 Vdc @ max 5 mA			
Enable input	Range: 0 ÷ 9 Vdc (OFF state), 15 ÷ 24 Vdc (ON state), 9 ÷ 15 Vdc (not accepted); Input impedance: Ri > 87kΩ			
Fault output	Output range : 0 ÷ 24 Vdc (ON state ≡ VL+ [logic power supply] ; OFF state ≡ 0 V) @ max 50 mA; external negative voltage not allowed (e.g. due to inductive loads)			
Pressure transducer power supply (only /W option)	+24Vdc @ max 100 mA (E-ATRA-7 see tech table GX800)			
Alarms	Solenoid not connected/short circuit, cable break with current reference signal, over/under temperature, current control monitoring, power supplies level, pressure transducer failure (/W option)			
Protection degree to DIN EN60529	IP66/67 with relevant cable gland			
Duty factor	Continuous rating (ED=100%)			
Tropicalization	Tropical coating on electronics PCB			
Additional characteristics	Short circuit protection of solenoid current supply; current control by P.I.D. with rapid solenoid switching; protection against reverse polarity of power supply			
Electromagnetic compatibility (EMC)	According to Directive 2014/30/UE (Immunity: EN 61000-6-2; Emission: EN 61000-6-3)			
Communication interface	USB Atos ASCII coding	CANopen EN50325-4 + DS408	PROFIBUS DP EN50170-2/IEC61158	EtherCAT EC 61158
Communication physical layer	not insulated USB 2.0 + USB OTG	optical insulated CAN ISO11898	optical insulated RS485	Fast Ethernet, insulated 100 Base TX

Note: a maximum time of 500 ms (depending on communication type) has to be considered between the driver energizing with the 24 Vdc power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero

8 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

Seals, recommended fluid temperature	NBR seals (standard) = -20°C ÷ +60°C, with HFC hydraulic fluids = -20°C ÷ +50°C FKM seals (/PE option) = -20°C ÷ +80°C CnBR low temp. seals (/BT option) = -40°C ÷ +60°C, with HFC hydraulic fluids = -20°C ÷ +50°C			
Recommended viscosity	20 ÷ 100 mm ² /s - max allowed range 15 ÷ 380 mm ² /s			
Max fluid contamination level	normal operation	ISO4406 class 18/16/13 NAS1638 class 7		see also filter section at
	longer life	ISO4406 class 16/14/11 NAS1638 class 5		www.atos.com or KTF catalog
Hydraulic fluid	Suitable seals type	Classification	Ref. Standard	
Mineral oils	NBR, FKM, NBR low temp.	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524	
Flame resistant without water	FKM	HFDU, HFDR	ISO 12922	
Flame resistant with water (1)	NBR, NBR low temp.	HFC		

 The ignition temperature of the hydraulic fluid must be 50°C higher than the max solenoid surface temperature

(1) Performance limitations in case of flame resistant fluids with water:

-max operating pressure = 210 bar -max fluid temperature = 50°C

9 CERTIFICATION DATA

Valve type	DPZA				
Certifications	Multicertification Group II ATEX IECEx CCC				
Solenoid	Single solenoid			Double solenoid	
Solenoid certified code	OZA-AES			OZA-AES, OZA-A	
Type examination certificate (1)	<ul style="list-style-type: none"> • ATEX: TUV IT 18 ATEX 068 X • IECEx: IECEx TPS 19.0004X • EAC: RU C - IT.AЖ38.B.00425/21 • CCC: 2024322307006321 			<ul style="list-style-type: none"> • ATEX: TUV IT 18 ATEX 068 X • IECEx: IECEx TPS 19.0004X • EAC: RU C - IT.AЖ38.B.00425/21 • CCC: 2024322307006321 • ATEX: CESI 02 ATEX 014 • IECEx: IECEx CES 10.0010x • EAC: RU C - IT.AЖ38.B.00425/21 • CCC: 2024322307005903 	
Method of protection	<ul style="list-style-type: none"> • ATEX Ex II 2G Ex db IIC T6/T5/T4 Gb; Ex II 2D Ex tb IIIC T85°C/T100°C/T135°C Db • IECEx, CCC Ex db IIC T6/T5/T4 Gb Ex tb IIIC T85°C/T100°C/T135°C Db • EAC 1Ex d IIC T6/T5/T4 Gb X; Ex tb IIIC T85°C/T100°C/T135°C Db X 			<ul style="list-style-type: none"> • ATEX Ex II 2G Ex db IIC T6/T5/T4 Gb; Ex II 2D Ex tb IIIC T85°C/T100°C/T135°C Db • IECEx, CCC Ex db IIC T6/T5/T4 Gb Ex tb IIIC T85°C/T100°C/T135°C Db • EAC 1Ex d IIC T6/T5/T4 Gb X; Ex tb IIIC T85°C/T100°C/T135°C Db X 	
Temperature class	T6	T5	T4	T4	T3
Surface temperature	≤ 85 °C	≤ 100 °C	≤ 135 °C	≤ 135 °C	≤ 200 °C
Ambient temperature (2)	-40 ÷ +40 °C	-40 ÷ +55 °C	-40 ÷ +70 °C	-40 ÷ +40 °C	-40 ÷ +70 °C
Applicable Standards	EN 60079-0 IEC 60079-0		EN 60079-1 IEC 60079-31		EN 60079-31 IEC 60079-1
Cable entrance: threaded connection	M = M20x1,5				

(1) The type examination certificates can be downloaded from www.atos.com

(2) The driver and solenoids are certified for minimum ambient temperature -40°C.

In case the complete valve must withstand with minimum ambient temperature -40°C, select **/BT** in the model code.

⚠ WARNING: service work performed on the valve by the end users or not qualified personnel invalidates the certification.

10 CABLE SPECIFICATION AND TEMPERATURE - Power supply and grounding cables have to comply with following characteristics:

Power supply and signals: section of wire = 1,0 mm ²	Grounding: section of external ground wire = 4 mm ²
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10.1 Cable temperature

The cable must be suitable for the working temperature as specified in the "safety instructions" delivered with the first supply of the products.

Max ambient temperature [°C]	Temperature class	Max surface temperature [°C]	Min. cable temperature [°C]
40 °C	T6	85 °C	80 °C
55 °C	T5	100 °C	90 °C
70 °C	T4	135 °C	110 °C

11 CABLE GLANDS

Cable glands with threaded connections M20x1,5 for standard or armoured cables have to be ordered separately, see tech table **KX800**

Note: a Loctite sealant type 545, should be used on the cable gland entry threads

12 HYDRAULIC OPTIONS

B = DPZA-**-5 = solenoid and integral electronics at side of port B of the main stage.

DPZA-**-7 = integral electronics at side of port B of the main stage.

D and E = Pilot and drain configuration can be modified as shown in section 13.

The valve's standard configuration provides internal pilot and external drain.

For different pilot / drain configuration select:

Option /D Internal drain

Option /E External pilot (through port X)

G = Pressure reducing valve installed between pilot valve and main body with fixed setting:

DPZA-1 and -2 = 28 bar

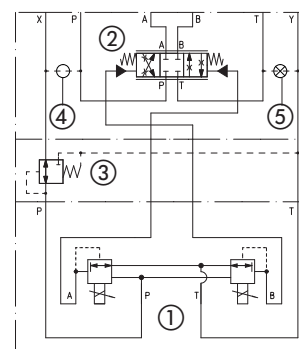
DPZA-4 and -6 = 40 bar

It is advisable for valves with internal pilot in case of system pressure higher than 150 bar.

FUNCTIONAL SCHEME

example of configuration 7*

3 positions, spring centered



① Pilot valve ② Main stage

③ Pressure reducing valve

④ Plug to be added for external pilot trough port X

⑤ Plug to be removed for internal drain through port T

13 ELECTRONIC OPTIONS

I = It provides 4 ÷ 20 mA current reference signal, instead of the standard ±10 VDC. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 Vdc or ±20 mA. It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.

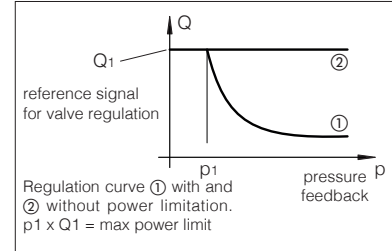
C = Only in combination with option **/W**

It is available to connect pressure transducer with 4 ÷ 20 mA current output signal, instead of the standard 0 ÷ 10 VDC. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ±20 mA.

W = Only for valves coupled with pressure compensator type HC-011 or KC-011 (see tech table D150). It provides the hydraulic power limitation function. The driver receives the flow reference signal by the analog input INPUT+ and a pressure transducer, installed in the hydraulic system, has to be connected to the driver's analog input TR. When the actual requested hydraulic power $p \times Q$ (TR x INPUT+) reaches the max power limit ($p_1 \times Q_1$), internally set by software, the driver automatically reduces the flow regulation of the valve. The higher is the pressure feedback the lower is the valve's regulated flow:

$$\text{Flow regulation} = \text{Min} \left(\frac{\text{PowerLimit [sw setting]}}{\text{Transducer Pressure [TR]}} ; \text{Flow Reference [INPUT+]} \right)$$

Hydraulic Power Limitation - option /W



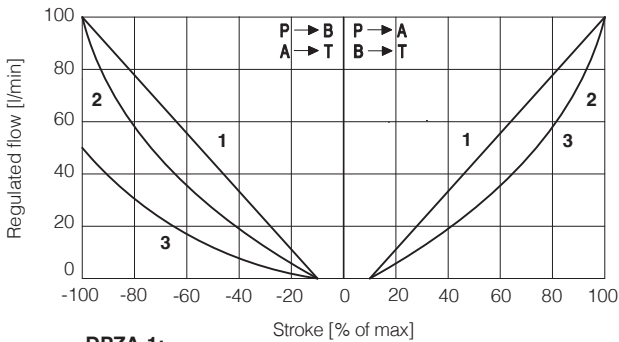
14 POSSIBLE COMBINED OPTIONS

Hydraulic options: all combination possible

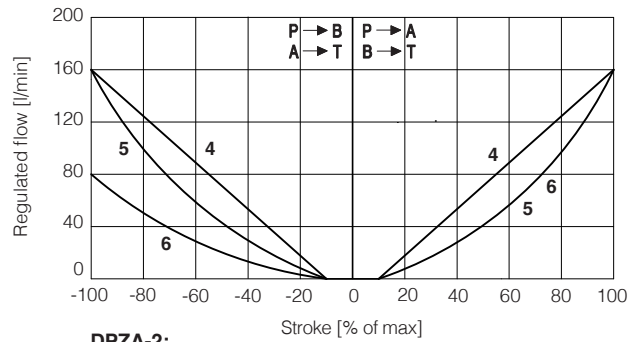
Electronics options: /IW, /CW, /CWI

15 DIAGRAMS (based on mineral oil ISO VG 46 at 50 °C)

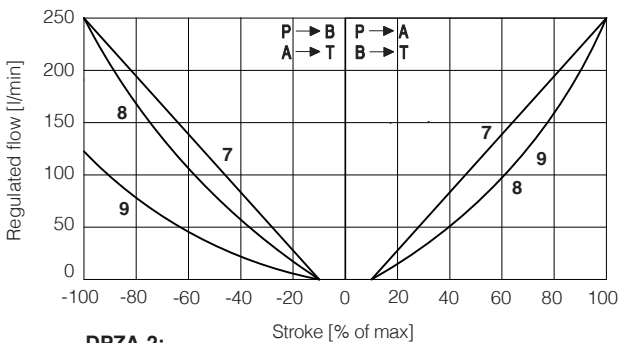
15.1 Regulation diagrams (values measure at Δp 10 bar P-T)



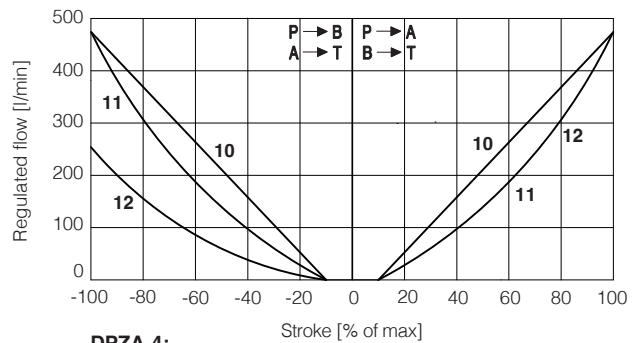
DPZA-1:
1 = L5 2 = S5 3 = D5



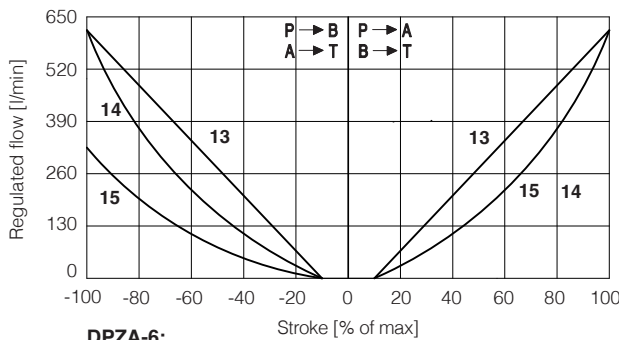
DPZA-2:
4 = L3 5 = S3 6 = D3



DPZA-2:
7 = L5 8 = S5 9 = D5



DPZA-4:
10 = L5 11 = S5 12 = D5



DPZA-6:
13 = L5 14 = S5 15 = D5

Note: Hydraulic configuration vs. reference signal for configuration 71 and 73 (standard and option /B)

Reference signal $\frac{0 \div +10 \text{ V}}{12 \div 20 \text{ mA}}$ } P → A / B → T


Reference signal $\frac{0 \div -10 \text{ V}}{12 \div 4 \text{ mA}}$ } P → B / A → T

16 POWER SUPPLY AND SIGNALS SPECIFICATIONS

Generic electrical output signals of the valve (e.g. fault or monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, ISO 4413).

16.1 Power supply (V+ and V0)

The power supply must be appropriately stabilized or rectified and filtered: apply at least a 10000 $\mu\text{F}/40\text{ V}$ capacitance to single phase rectifiers or a 4700 $\mu\text{F}/40\text{ V}$ capacitance to three phase rectifiers.

 A safety fuse is required in series to each power supply: 2,5 A time lag fuse.

16.2 Power supply for driver's logic and communication (VL+ and VL0)

The power supply for driver's logic and communication must be appropriately stabilized or rectified and filtered: apply at least a 10000 $\mu\text{F}/40\text{ V}$ capacitance to single phase rectifiers or a 4700 $\mu\text{F}/40\text{ V}$ capacitance to three phase rectifiers.

The separate power supply for driver's logic on pin 3 and 4, allow to remove solenoid power supply from pin 1 and 2 maintaining active the diagnostics, USB and fieldbus communications.

 A safety fuse is required in series to each driver's logic and communication power supply: 500 mA fast fuse.

16.3 Flow reference input signal (INPUT+)

The driver controls in closed loop the valve spool position proportionally to the external reference input signal.

Reference input signal is factory preset according to selected valve code, defaults are $\pm 10\text{ Vdc}$ for standard and $4 \div 20\text{ mA}$ for /I option.

Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of $\pm 10\text{ VDC}$ or $\pm 20\text{ mA}$.

Drivers with fieldbus interface can be software set to receive reference signal directly from the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range $0 \div 24\text{VDC}$.

16.4 Monitor output signals (MONITOR and MONITOR2)

The driver generates an analog output signal (MONITOR) proportional to the actual coil current of the valve; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, fieldbus reference).

Monitor output signal is factory preset according to selected valve code, default settings is $\pm 5\text{ VDC}$ ($1\text{V} = 1\text{A}$).

Output signal can be reconfigured via software, within a maximum range of $\pm 5\text{ Vdc}$.

Option /W

The driver generates a second analog output signal (MONITOR2) proportional to the actual system pressure.

The output maximum range is $\pm 5\text{ VDC}$; default setting is $0 \div 5\text{ VDC}$

16.5 Enable input signal (ENABLE)

To enable the driver, supply a 24 Vdc on pin 6: Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to active the communication and the other driver functions when the valve must be disabled for safety reasons. This condition **does not comply** with norms IEC 61508 and ISO 13849.

Enable input signal can be used as generic digital input by software selection.

16.6 Fault output signal (FAULT)

Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for $4 \div 20\text{ mA}$ input, spool position transducer cable broken, etc.). Fault presence corresponds to 0 Vdc, normal working corresponds to 24 Vdc.

Fault status is not affected by the Enable input signal. Fault output signal can be used as digital output by software selection.

16.7 Remote Pressure Transducer Input signal (TR) - only for /W option

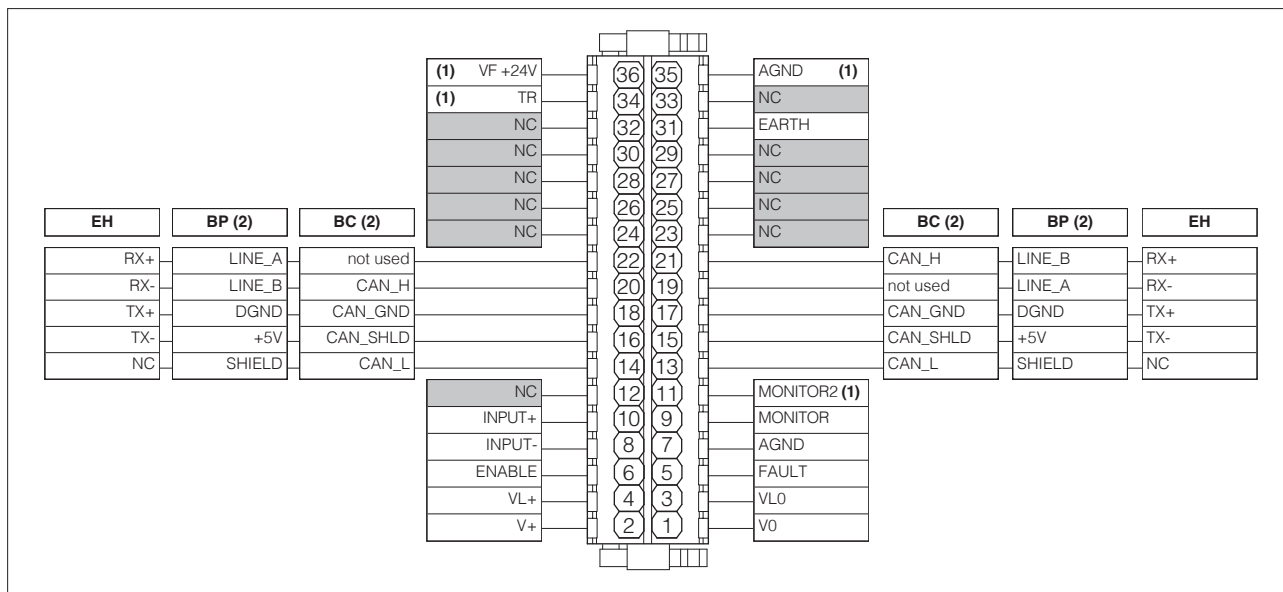
Analog pressure transducers can be directly connected to the driver.

Analog input signal is factory preset according to selected valve code, defaults are $0 \div 10\text{ Vdc}$ for standard and $4 \div 20\text{ mA}$ for /C option.

Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of $\pm 10\text{ VDC}$ or $\pm 20\text{ mA}$.

Note: transducer feedback can be read as a digital information through fieldbus communication - software selectable.

17 TERMINAL BOARD OVERVIEW



(1) Connections available only for /W option

(2) For BC and BP executions the fieldbus connections have an internal pass-through connection

18 ELECTRONIC CONNECTIONS

18.1 Main connections signals

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES
A	1	V0	Power supply 0 Vdc	Gnd - power supply
	2	V+	Power supply 24 Vdc	Input - power supply
	3	VL0	Power supply 0 Vdc for driver's logic and communication	Gnd - power supply
	4	VL+	Power supply 24 Vdc for driver's logic and communication	Input - power supply
	5	FAULT	Fault (0 Vdc) or normal working (24 Vdc), referred to VL0	Output - on/off signal
	6	ENABLE	Enable (24 Vdc) or disable (0 Vdc) the driver, referred to VL0	Input - on/off signal
	7	AGND	Analog ground	Gnd - analog signal
	8	INPUT-	Negative reference input signal for INPUT+	Input - analog signal
	9	MONITOR	Monitor output signal: ± 5 Vdc maximum range, referred to AGND Default is: ± 5 Vdc	Output - analog signal Software selectable
	10	INPUT+	Reference input signal: ± 10 Vdc / ± 20 mA maximum range Defaults are: ± 10 Vdc for standard and $4 \div 20$ mA for /I option	Input - analog signal Software selectable
	11	MONITOR2	2nd monitor output signal: ± 5 Vdc maximum range, referred to AGND (1) Default is: $0 \div 5$ Vdc	Output - analog signal Software selectable
31	EARTH	Internally connected to driver housing		

(1) 2nd monitor output signal is available only for /W option

18.2 USB connector - M12 - 5 pin always present

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
B	1	+5V_USB	Power supply
	2	ID	Identification
	3	GND_USB	Signal zero data line
	4	D-	Data line -
	5	D+	Data line +

Driver view
(female)

18.3 BC fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
C1	14	CAN_L	Bus line (low)
	16	CAN_SHLD	Shield
	18	CAN_GND	Signal zero data line
	20	CAN_H	Bus line (high)
	22	not used	Pass-through connection (1)

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
C2	13	CAN_L	Bus line (low)
	15	CAN_SHLD	Shield
	17	CAN_GND	Signal zero data line
	19	not used	Pass-through connection (1)
	21	CAN_H	Bus line (high)

(1) pin 19 and 22 can be fed with external +5V supply of CAN interface

18.4 BP fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
C1	14	SHIELD	
	16	+5V	Power supply
	18	DGND	Data line and termination signal zero
	20	LINE_B	Bus line (low)
	22	LINE_A	Bus line (high)

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
C2	13	SHIELD	
	15	+5V	Power supply
	17	DGND	Data line and termination signal zero
	19	LINE_A	Bus line (high)
	21	LINE_B	Bus line (low)

18.5 EH fieldbus execution connections

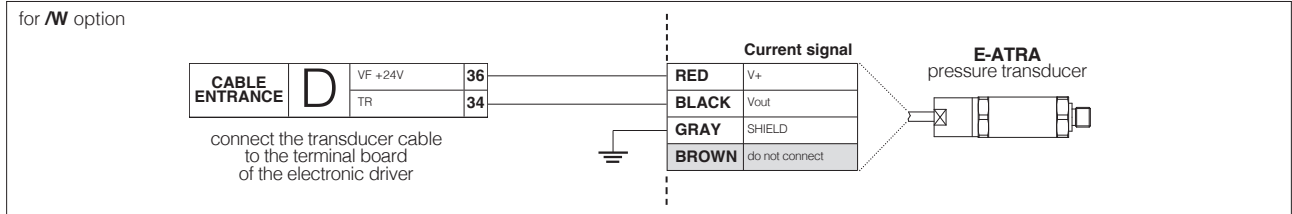
CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
C1 (input)	14	NC	do not connect
	16	TX-	Transmitter
	18	TX+	Transmitter
	20	RX-	Receiver
	22	RX+	Receiver

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
C2 (output)	13	NC	do not connect
	15	TX-	Transmitter
	17	TX+	Transmitter
	19	RX-	Receiver
	21	RX+	Receiver

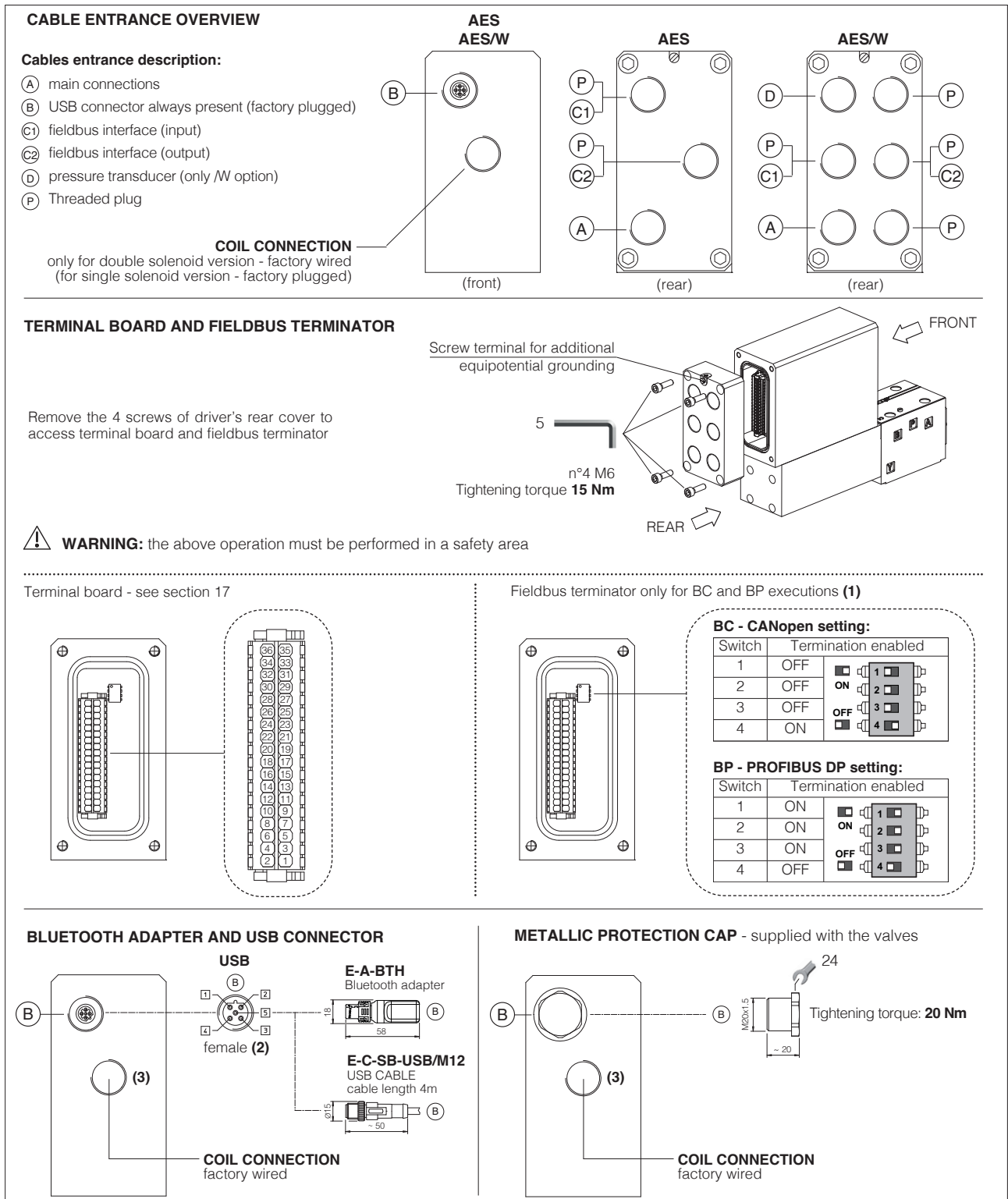
17.6 Remote pressure transducer connector - only for /W option

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES	Voltage	Current
D	34	TR	Signal transducer ± 10 Vdc / ± 20 mA maximum range	Input - analog signal Software selectable	Connect	Connect
	35	AGND	Common gnd for transducer power and signals	Common gnd	Connect	/
	36	VF +24V	Power supply +24Vdc	Output - power supply	Connect	Connect

E-ATRA remote pressure transducer connection - see tech table **GX800**

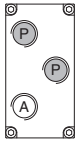
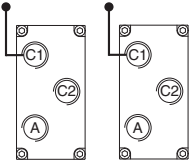
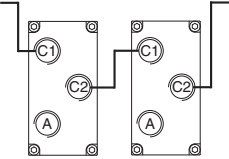


19 CONNECTIONS LAYOUT

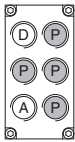
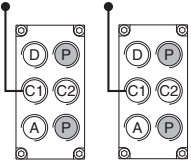
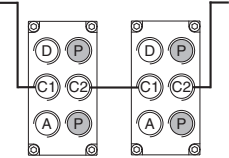


(1) Drivers with BC and BP fieldbus interface are delivered by default 'Not Terminated'. All switches are set OFF
(2) Pin layout always referred to driver's view
(3) For configuration 51 and 53 do not remove the metallic protection cap

19.1 Cable glands and threaded plug for AES - see tech table KX800

Communication interfaces	To be ordered separately				Cable entrance overview	Notes
	Cable gland quantity	entrance	Threaded plug quantity	entrance		
NP	1	A	none	none		Cable entrance P are factory plugged Cable entrance A is open for costumers
BC, BP, EH "via stub" connection	2	C1 A	1	C2		Cable entrance A, C1, C2 are open for costumers
BC, BP, EH "daisy chain" connection	3	C1 C2 A	none	none		Cable entrance A, C1, C2 are open for costumers

19.2 Cable glands and threaded plug for AES with /W option - see tech table KX800

Communication interfaces	To be ordered separately				Cable entrance overview	Notes
	Cable gland quantity	entrance	Threaded plug quantity	entrance		
NP	2	D A	none	none		Cable entrance P are factory plugged Cable entrance A, D are open for costumers
BC, BP, EH "via stub" connection	3	D C1 A	1	C2		Cable entrance P are factory plugged Cable entrance A, C1, C2, D are open for costumers
BC, BP, EH "daisy chain" connection	4	D C1 - C2 A	none	none		Cable entrance P are factory plugged Cable entrance A, C1, C2, D are open for costumers

20 PLUGS LOCATION FOR PILOT/DRAIN CHANNELS

Depending on the position of internal plugs, different pilot/drain configurations can be obtained as shown below.
To modify the pilot/drain configuration, proper plugs must only be interchanged. The plugs have to be sealed using loctite 270.
Standard valves configuration provides internal pilot and external drain

DPZA-1	Pilot channels	Drain channels	<p>Internal piloting: blinded plug SP-X300F ① in X; External piloting: blinded plug SP-X300F ② in Pp; Internal drain: blinded plug SP-X300F ③ in Y; External drain: blinded plug SP-X300F ④ in Dr.</p>
DPZA-2	Pilot channels	Drain channels	<p>Internal piloting: Without blinded plug SP-X300F ①; External piloting: Add blinded plug SP-X300F ①; Internal drain: Without blinded plug SP-X300F ②; External drain: Add blinded plug SP-X300F ②.</p>
DPZA-4	Pilot channels	Drain channels	<p>Internal piloting: Without blinded plug SP-X500F ①; External piloting: Add blinded plug SP-X500F ①; Internal drain: Without blinded plug SP-X300F ②; External drain: Add blinded plug SP-X300F ②.</p>
DPZO-6	Pilot channels	Drain channels	<p>Internal piloting: Without plug ①; External piloting: Add DIN-908 M16x1,5 in pos ①; Add plug SP-X325A in pos ②; Internal drain: Without blinded plug SP-X300F ③; External drain: Add blinded plug SP-X300F ③.</p> <p>To reach the orifice ② remove plug ④ = G1/8"</p>

21 FASTENING BOLTS AND SEALS

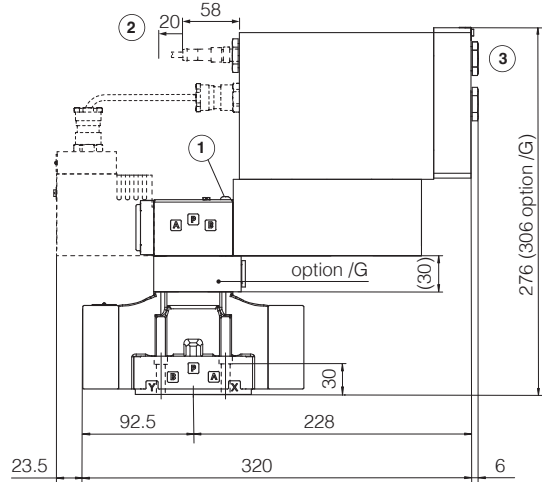
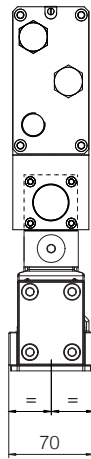
Type	Size	Fastening bolts	Seals
DPZA	1 = 10	4 socket head screws M6x40 class 12.9 Tightening torque = 15 Nm	5 OR 2050; Diameter of ports A, B, P, T: Ø 11 mm (max) 2 OR 108 Diameter of ports X, Y: Ø = 5 mm (max)
	2 = 16	4 socket head screws M10x50 class 12.9 Tightening torque = 70 Nm 2 socket head screws M6x45 class 12.9 Tightening torque = 15 Nm	4 OR 130; Diameter of ports A, B, P, T: Ø 20 mm (max) 2 OR 2043 Diameter of ports X, Y: Ø = 7 mm (max)
	4 = 25	6 socket head screws M12x60 class 12.9 Tightening torque = 125 Nm	4 OR 4112; Diameter of ports A, B, P, T: Ø 24 mm (max) 2 OR 3056 Diameter of ports X, Y: Ø = 7 mm (max)
	6 = 32	6 socket head screws M20x80 class 12.9 Tightening torque = 600 Nm	4 OR 144; Diameter of ports A, B, P, T: Ø 34 mm (max) 2 OR 3056 Diameter of ports X, Y: Ø = 7 mm (max)

DPZA-AES-*-1

ISO 4401: 2005

Mounting surface: 4401-05-05-0-05 (see table P005)

Mass [kg]	
DPZA-*-15*	14,7
DPZA-*-17*	16,4
Option /G	+0,9



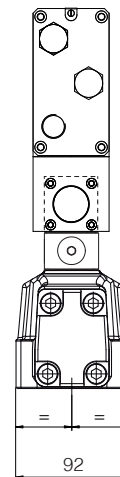
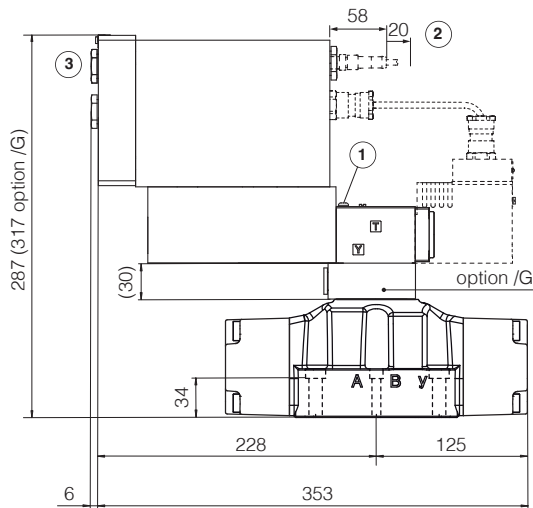
Dotted line = double solenoid version

DPZA-AES-*-2

ISO 4401: 2005

Mounting surface: 4401-07-07-0-05 (see table P005)

Mass [kg]	
DPZA-*-25*	18,9
DPZA-*-27*	20,6
Option /G	+0,9



Dotted line = double solenoid version

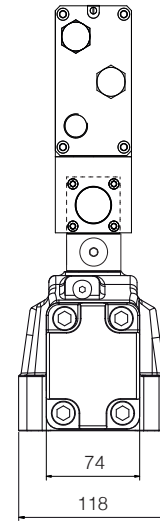
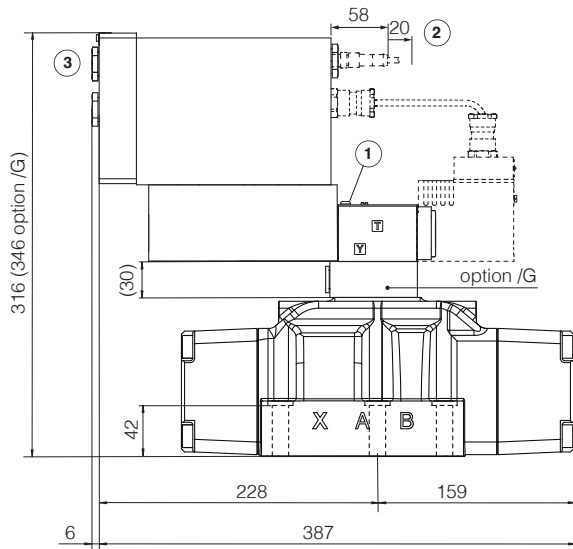
- ① = Air bleed off
- ② = Space required for connection cable and for Bluetooth adapter or USB connector removal
- ③ = The dimensions of cable glands must be considered (see tech table **KX800**)

DPZA-AES-*-4

ISO 4401: 2005

Mounting surface: 4401-08-08-0-05 (see table P005)

Mass [kg]	
DPZA-*-45*	24,1
DPZA-*-47*	25,8
Option /G	+0,9



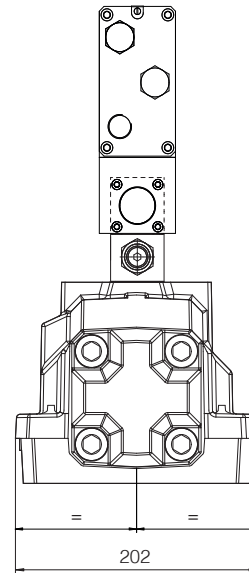
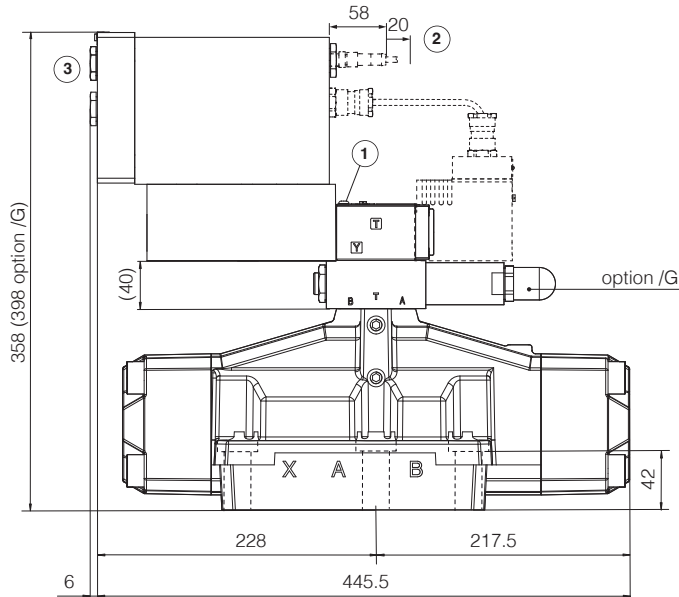
Dotted line = double solenoid version

DPZA-AES-*-6

ISO 4401: 2005

Mounting surface: 4401-10-09-0-05

Mass [kg]	
DPZA-*-65*	49,2
DPZA-*-67*	50,9
Option /G	+0,9



Dotted line = double solenoid version

- ① = Air bleed off
- ② = Space required for connection cable and for Bluetooth adapter or USB connector removal
- ③ = The dimensions of cable glands must be considered (see tech table **KX800**)

23 RELATED DOCUMENTATION

X010 Basics for electrohydraulics in hazardous environments
X020 Summary of Atos ex-proof components certified to ATEX, IECEx, EAC, PESO, CCC
FX900 Operating and maintenance information for ex-proof proportional valves
GS500 Programming tools
GS510 Fieldbus

GX800 Ex-proof pressure transducer type E-ATRA-7
KX800 Cable glands for ex-proof valves
P005 Mounting surfaces for electrohydraulic valves
E-MAN-RA-AES AES user manual